



DESCRIPTION

A stepper motor to satisfy all your robotics needs! This 4-wire bipolar stepper has 1.8° per step for smooth motion and a nice holding torque. The motor was specified to have a max current of 350mA so that it could be driven easily with an <u>Adafruit motor shield for Arduino</u> (or other motor driver) and a wall adapter or lead-acid battery.

Some nice details include a ready-to-go cable and a machined drive shaft (so you can easily attach stuff). We drove it with an <u>Adafruit motor shield for Arduino</u> and it hummed along nicely at 50 RPM. To connect to our shield, put the wires in this order: Red, Yellow, skip ground, Green, Brown (or Gray)

TECHNICAL DETAILS

- 200 steps per revolution, 1.8 degrees
- Coil #1: Red & Yellow wire pair. Coil #2 Green & Brown/Gray wire pair.
- Bipolar stepper, requires 2 full H-bridges!
- 4-wire, 8 inch leads
- 42mm/1.65" square body
- 31mm/1.22" square mounting holes, 3mm metric screws (M3)
- 5mm diameter drive shaft, 24mm long, with a machined flat
- 12V rated voltage (you can drive it at a lower voltage, but the torque will drop) at 350mA max current
- 28 oz*in, 20 N*cm, 2 Kg*cm holding torque per phase
- 35 ohms per winding